

知识编辑

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总结

任务简介

背景：

- ▶ 知识可能是错误或者过时的

77 You

梅西是否获得过世界杯冠军？

ChatGPT

截至我知识截止日期2022年1月，梅西在阿根廷国家队中还没有获得过世界杯冠军。然而，他曾多次代表阿根廷参加国际比赛，包括世界杯，而且在2014年的巴西世界杯上，阿根廷队进入决赛，但最终输给了德国队，屈居亚军。梅西是一位备受尊敬的足球运动员，他在俱乐部水平上多次获得荣誉，但在国家队层面上，直到2022年1月，他还未获得世界杯冠军。请注意，关于梅西的最新信息可能发生了变化，建议查阅最新的体育新闻以获取最新信息。

77 You

2023年NBA总决赛冠军是那个队伍？

ChatGPT

很抱歉，截至我知识截止日期2022年1月，我无法提供2023年NBA总决赛冠军的信息，因为我的培训数据截止于2022年，并且我无法浏览互联网以获取实时信息。要获取最新的NBA冠军信息，建议查阅最新的体育新闻报道、官方NBA网站或其他可靠的体育新闻来源。

77 You 梅西是否获得过世界杯冠军？

是的，梅西获得过世界杯冠军。梅西获得过两次世界杯冠军，分别是2014年和2018年世界杯。

由文心大模型 3.5 生成



77 You 2023年NBA总决赛冠军是那个队伍？

2023年NBA总决赛冠军是掘金队。

由文心大模型 3.5 生成



77 You 2024年NBA总决赛冠军是那个队伍？

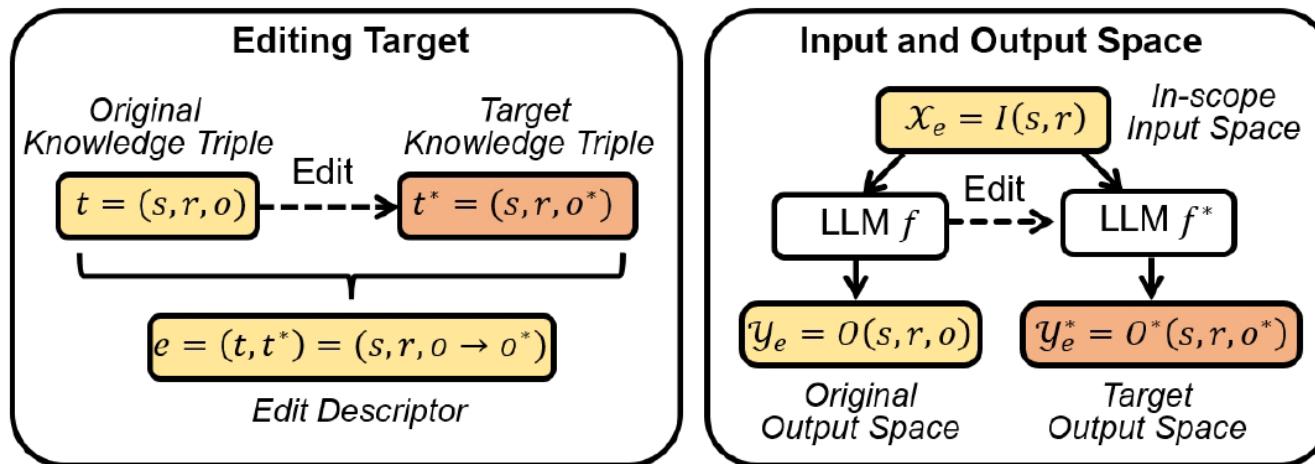
很抱歉，我无法预测未来的2024年NBA总决赛冠军。未来是不确定的，比赛结果由许多因素决定，包括球队实力、球员健康状况、教练策略等。预测未来的比赛结果是非常困难的，而且没有确凿的证据支持任何一支队伍将赢得总冠军。

由文心大模型 3.5 生成

任务简介

任务介绍：

原始知识: $t = (s, r, o)$ \longrightarrow 目标知识: $t^* = (s, r, o^*)$



$$\begin{aligned} & \min \mathbb{E}_{e \in \mathcal{E}} \mathbb{E}_{x, y^* \in X_e, Y_e^*} \mathcal{L}(f^*(x), y^*), \text{ where } f^* = M(f; \mathcal{E}), \\ & \text{s.t. } f^*(x) = f(x), \quad \forall x \in \mathcal{X} \setminus \mathcal{X}_{\mathcal{E}}, \end{aligned}$$

任务简介

✿ 评价指标：

- ▶ 可靠性(Reliability)：编辑知识的成功率；

$$\mathbb{E}_{x'_e, y'_e \sim \{(x_e, y_e)\}} \mathbb{1} \left\{ \operatorname{argmax}_y f_{\theta_e} (y \mid x'_e) = y'_e \right\}$$

- ▶ 局部性(Locality)：控制编辑范围内的输出变化，不影响无关知识；

$$\mathbb{E}_{x'_e, y'_e \sim O(x_e, y_e)} \mathbb{1} \left\{ f_{\theta_e} (y \mid x'_e) = f_{\theta} (y \mid x'_e) \right\}$$

- ▶ 泛化性(Generality)：编辑范围内的成功率；

$$\mathbb{E}_{x'_e, y'_e \sim N(x_e, y_e)} \mathbb{1} \left\{ \operatorname{argmax}_y f_{\theta_e} (y \mid x'_e) = y'_e \right\}$$

任务简介

✿ 数据集：

```
{  
    "subject": "Panzer 58",  
    "src": "What year was Panzer 58 commissioned?",  
    "rephrase": "What year was the date for the launch of the Panzer 58?",  
    "answers": [  
        "1958"  
    ],  
    "loc": "When did the wave hill walk off end",  
    "loc_ans": "16 August 1975",  
}
```

Task	Edit Descriptor e	In-scope Input $x \sim X_e$	Original Output $y \sim \mathcal{Y}_e$	Target Output $y \sim \mathcal{Y}_e^*$
QA	(Kazakhstan, Capital, Astana→Nur-Sultan)	What is the capital of Kazakhstan?	Astana	Nur-Sultan
FC	(Marathon, Record, Kipchoge→Kiptum)	Kipchoge holds the men's marathon world record.	True	False
NLG	(Jordan Poole, Play In, Warriors→Wizards)	Provide a short introduction to Jordan Poole, describing his current position.	Jordan Poole entered the Warriors' rotation recently.	In 2023, Jordan Poole transitioned from the Warriors to the Wizards, marking a significant change.

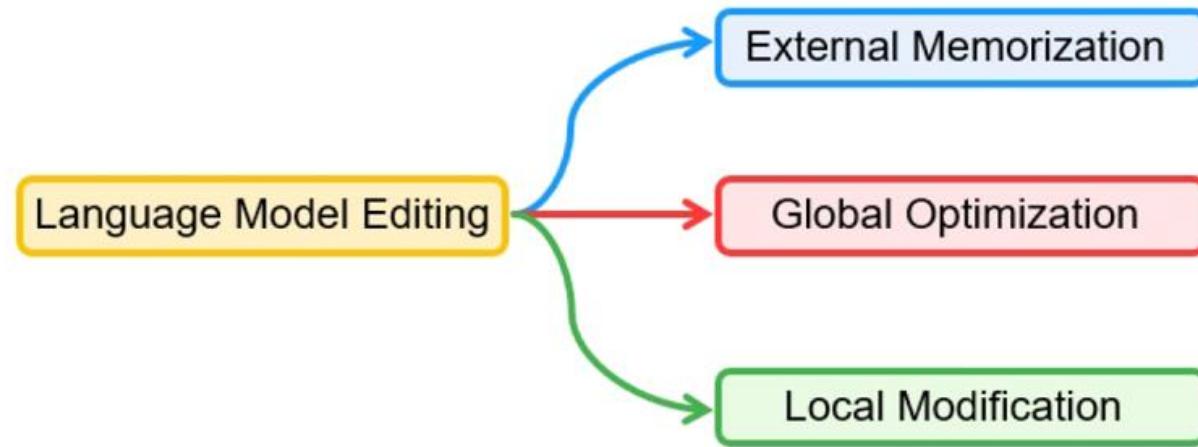
✿ 相关数据集：

- ▶ 生成任务：zsRE、WikiGen、T-REx-100 & T-REx-1000、CounterFact、ParaRel、NQ-Situated、MQuAKE
- ▶ 分类任务：FEVER、ConvSent、Bias in Bios、VitaminC-FC

任务简介

方法分类：

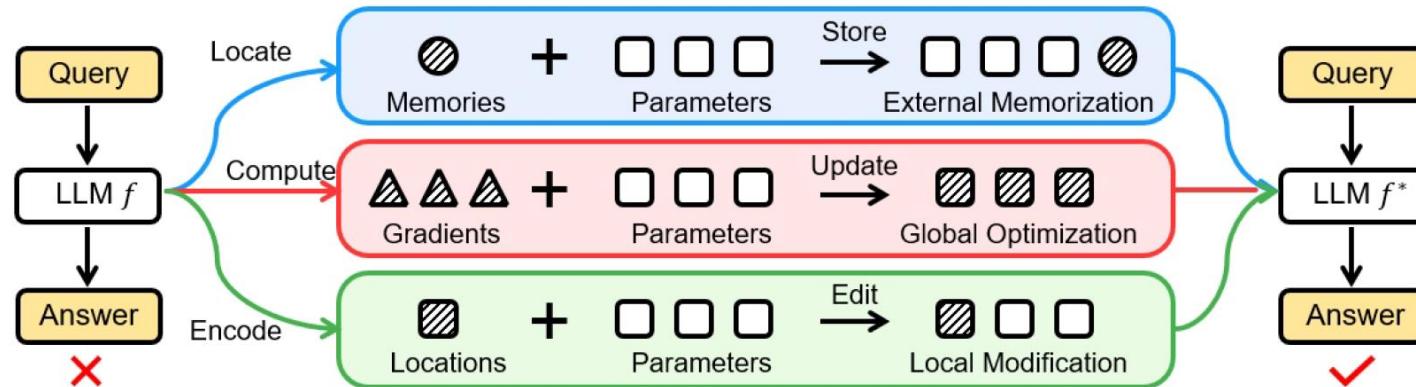
- ▶ External Memorization：利用外部结构存储新知识进行编辑，无需修改LLM的权重。
- ▶ Global Optimization：在新知识的指导下通过优化将新知识纳入LLM中。
- ▶ Local Modification：定位LLM中特定知识的相关参数并进行更新。



任务简介

方法分类：

- ▶ External Memorization：利用外部结构存储新知识进行编辑，无需修改LLM的权重。
- ▶ Global Optimization：在新知识的指导下通过优化将新知识纳入LLM中。
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目录

2.

相关工作

MQUAKE

	Recall	Edited Fact	Model Before Edit	Model After Edit
Our Question	Who is the current British Prime Minister ?		Boris Johnson 	Rishi Sunak
	Recall	Related Fact		
		Who is currently the head of the British government ?	Boris Johnson 	Rishi Sunak
		Who is married to the British Prime Minister ?	Carrie Johnson 	Carrie Johnson
New Fact: The current British Prime Minister is Rishi Sunak .				

- 现有的知识编辑方法通常在回答编辑事实的释义问题时表现良好，但在回答因编辑事实而改变答案的问题时却表现不佳。
- 提出一个跨跳问答数据MQUAKE，包括MQUAKE-CF(反事实编辑)、MQUAKE-T(时序知识)

$$\mathcal{C} = \langle (s_1, r_1, o_1), \dots, (s_n, r_n, o_n) \rangle$$

MQUAKE

-
- \mathcal{E} (WALL-E, creator, Andrew Stanton → James Watt)
(University of Glasgow, headquarters location,
Glasgow → Beijing)
-
- \mathcal{Q} In which city is the headquarters of the employer of
WALL-E's creator located?
What is the location of the headquarters of the company
that employed the creator of WALL-E?
Where is the headquarters of the company that employed
the creator of WALL-E situated?
-
- a Emeryville
 a^* Beijing
-
- \mathcal{C} (WALL-E, creator, Andrew Stanton)
(Andrew Stanton, employer, Pixar)
(Pixar, headquarters location, Emeryville)
-
- \mathcal{C}^* (WALL-E, creator, James Watt)
(James Watt, employer, University of Glasgow)
(University of Glasgow, headquarters location, Beijing)
-

构建数据集：

- ▶ MQUAKE-CF：知识三元组来源为Wikidata，问题 \mathcal{Q} 通过ChatGPT构建，取样替换 o 为 o^* 构建新知识；
- ▶ MQUAKE-T：基于时间的现实世界知识更新

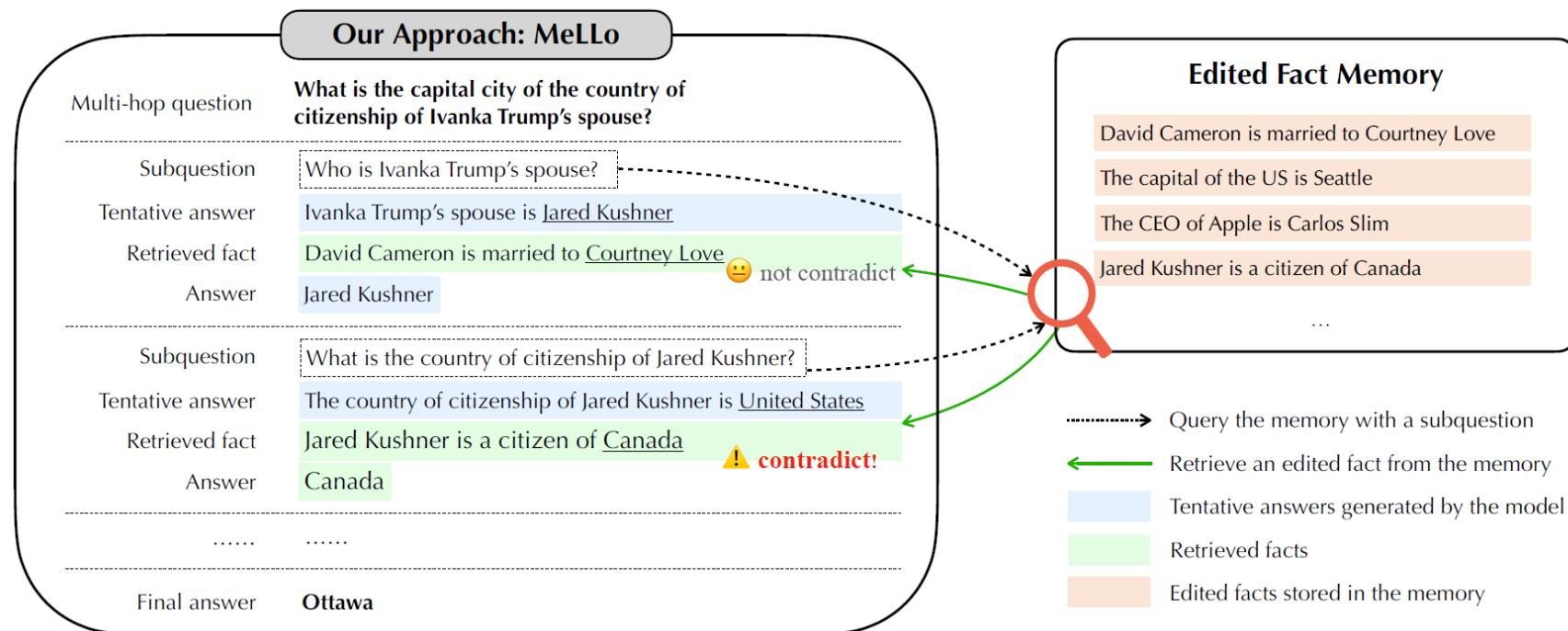
Wikidata 2021-04 / 2023-04

	#Edits	2-hop	3-hop	4-hop	Total
MQUAKE-CF	1	2,454	855	446	3,755
	2	2,425	853	467	3,745
	3	-	827	455	1,282
	4	-	-	436	436
	All	4,879	2,535	1,804	9,218
MQUAKE-T	1 (All)	1,421	445	2	1,868

MQUAKE

❖ MQUAKE:

- ▶ 将多跳问题分解为子问题；
- ▶ 回答子问题的答案；
- ▶ 自我检查答案是否与Memory中任何已编辑的事实矛盾；



MQUAKE

实验结果：

MQUAKE-CF

Base Model	Method	Edit-wise	Instance-wise	Multi-hop	Multi-hop (CoT)
GPT-J	Base	—	100.0	43.4	42.1
	FT	44.1	24.1	1.6 ↓41.8	1.9 ↓40.2
	MEND	72.8	59.6	9.2 ↓34.2	11.5 ↓30.6
	ROME	90.8	86.7	7.6 ↓35.8	18.1 ↓24.0
	MEMIT	97.4	94.0	8.1 ↓35.3	12.3 ↓29.8
Vicuna-7B	Base	—	61.0	30.0	36.6
	FT	20.2	7.8	0.7 ↓29.3	0.2 ↓36.4
	MEND	65.2	47.6	7.4 ↓22.6	8.4 ↓28.2
	ROME	99.8	89.6	8.4 ↓21.6	12.2 ↓24.4
	MEMIT	96.6	84.0	7.6 ↓22.4	9.0 ↓27.6

MQUAKE-T

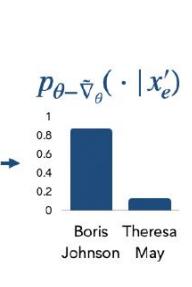
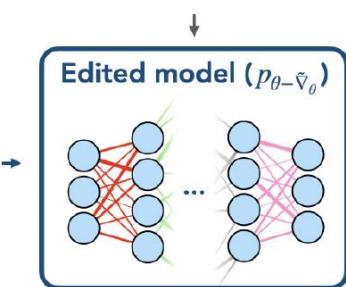
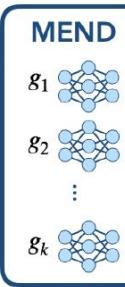
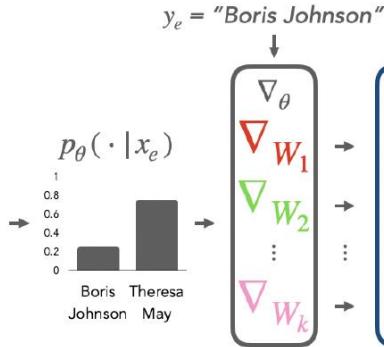
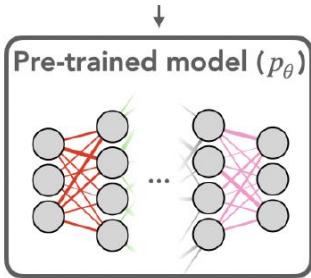
Method	Edit-wise	Instance-wise	Multi-hop	Multi-hop (CoT)
Base	—	100.0	34.3	46.8
FT	19.5	19.0	0.0 ↓34.3	0.2 ↓46.6
MEND	99.0	98.5	16.0 ↓18.3	38.2 ↓8.6
ROME	100.0	97.7	0.3 ↓34.0	11.3 ↓35.5
MEMIT	100.0	98.9	0.3 ↓34.0	4.8 ↓42.0

# Edited instances	MQUAKE-CF				MQUAKE-T			
	1	100	1000	3000	1	100	500	1868
Base Model	Method							
GPT-J	MEMIT	12.3	9.8	8.1	1.8	4.8	1.0	0.2
GPT-J	MEND	11.5	9.1	4.3	3.5	38.2	17.4	12.7
GPT-J	MeLLo	20.3	12.5	10.4	9.8	85.9	45.7	33.8
Vicuna-7B	MeLLo	20.3	11.9	11.0	10.2	84.4	56.3	52.6
GPT-3	MeLLo	68.7	50.5	43.6	41.2	91.1	87.4	86.2
								85.5

MEND

Editing a Pre-Trained Model with MEND

$x_e = \text{"Who is the prime minister of the UK?"}$

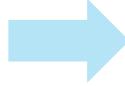


$$z_{\ell+1} = W_\ell u_\ell$$

$$\frac{\partial L}{\partial W_\ell^{ij}} = \sum_k \frac{\partial L}{\partial z_{\ell+1}^k} \frac{\partial z_{\ell+1}^k}{\partial W_\ell^{ij}} = \frac{\partial L}{\partial z_{\ell+1}^i} \frac{\partial z_{\ell+1}^i}{\partial W_\ell^{ij}}$$

$$\frac{\partial L}{\partial W_\ell^{ij}} = \delta_{\ell+1}^i u_\ell^j$$

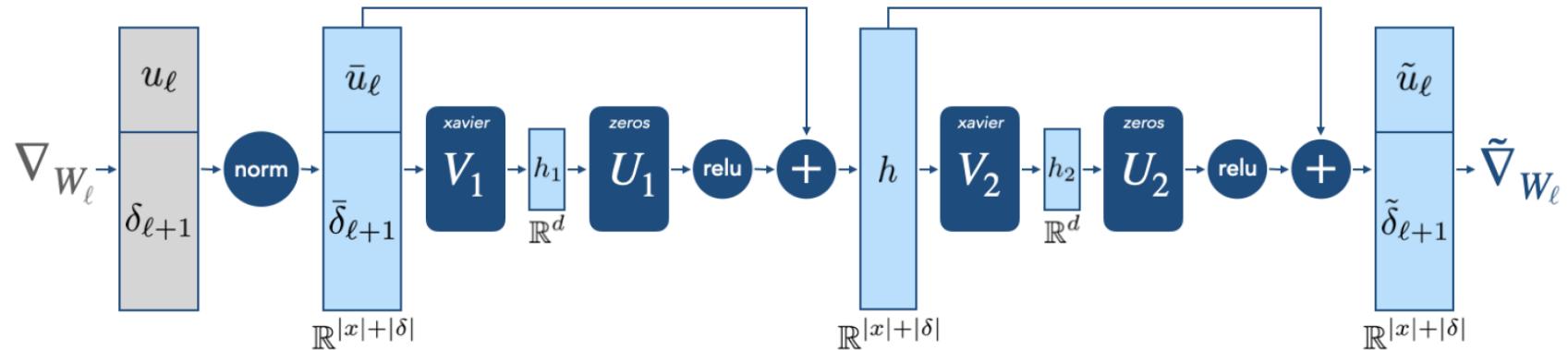
$$\nabla_{W_\ell} L = \sum_{i=1}^B \delta_{\ell+1}^i u_\ell^i {}^\top$$



$$\tilde{\nabla}_{W_\ell} = \sum_{i=1}^B \delta_{\ell+1}^i \tilde{u}_\ell^i {}^\top.$$

$$\tilde{W} = W_\ell - \alpha \tilde{\nabla}_{W_\ell}$$

MEND Architecture



$$z_\ell = \text{concat}(u_\ell, \delta_{\ell+1})$$

$$h_\ell = z_\ell + \sigma(s_\ell^1 \odot (U_1 V_1 z_\ell + b) + o_\ell^1), \quad g(z_\ell) = h_\ell + \sigma(s_\ell^2 \odot U_2 V_2 h_\ell + o_\ell^2)$$

$$\tilde{\nabla}_{W_\ell} = \sum_{i=1}^B \tilde{\delta}_{\ell+1}^i \tilde{u}_\ell^{i\top}.$$

$$\tilde{W} = W_\ell - \alpha \tilde{\nabla}_{W_\ell}$$

MEND

✿ 训练过程:

Algorithm 1 MEND Training

- 1: **Input:** Pre-trained p_{θ_W} , weights to make editable \mathcal{W} , editor params ϕ_0 , edit dataset D_{edit}^{tr} , edit-locality tradeoff c_{edit}
 - 2: **for** $t \in 1, 2, \dots$ **do**
 - 3: Sample $x_e, y_e, x'_e, y'_e, x_{loc} \sim D_{edit}^{tr}$
 - 4: $\tilde{\mathcal{W}} \leftarrow \text{EDIT}(\theta_W, \mathcal{W}, \phi_{t-1}, x_e, y_e)$
 - 5: $L_e \leftarrow -\log p_{\theta_{\tilde{\mathcal{W}}}}(y'_e | x'_e)$
 - 6: $L_{loc} \leftarrow \text{KL}(p_{\theta_W}(\cdot | x_{loc}) \| p_{\theta_{\tilde{\mathcal{W}}}}(\cdot | x_{loc}))$
 - 7: $L(\phi_{t-1}) \leftarrow c_{edit} L_e + L_{loc}$
 - 8: $\phi_t \leftarrow \text{Adam}(\phi_{t-1}, \nabla_{\phi} L(\phi_{t-1}))$
-

Algorithm 2 MEND Edit Procedure

- 1: **procedure** EDIT($\theta, \mathcal{W}, \phi, x_e, y_e$)
 - 2: $\hat{p} \leftarrow p_{\theta_W}(y_e | x_e)$, **caching** input u_ℓ to $W_\ell \in \mathcal{W}$
 - 3: $L(\theta, \mathcal{W}) \leftarrow -\log \hat{p}$ ▷ Compute NLL
 - 4: **for** $W_\ell \in \mathcal{W}$ **do**
 - 5: $\delta_{\ell+1} \leftarrow \nabla_{W_\ell u_\ell + b_\ell} l_e(x_e, y_e)$ ▷ Grad wrt output
 - 6: $\tilde{u}_\ell, \tilde{\delta}_{\ell+1} \leftarrow g_{\phi_\ell}(u_\ell, \delta_{\ell+1})$ ▷ Pseudo-acts/deltas
 - 7: $\tilde{W}_\ell \leftarrow W_\ell - \tilde{\delta}_{\ell+1} \tilde{u}_\ell^\top$ ▷ Layer ℓ model edit
 - 8: $\tilde{\mathcal{W}} \leftarrow \{\tilde{W}_1, \dots, \tilde{W}_k\}$
 - 9: **return** $\tilde{\mathcal{W}}$ ▷ Return edited weights
-

MEND losses: $L_e = -\log p_{\theta_{\tilde{\mathcal{W}}}}(y'_e | x'_e), L_{loc} = \text{KL}(p_{\theta_W}(\cdot | x_{loc}) \| p_{\theta_{\tilde{\mathcal{W}}}}(\cdot | x_{loc}))$. (4a,b)

MEND

实验结果：

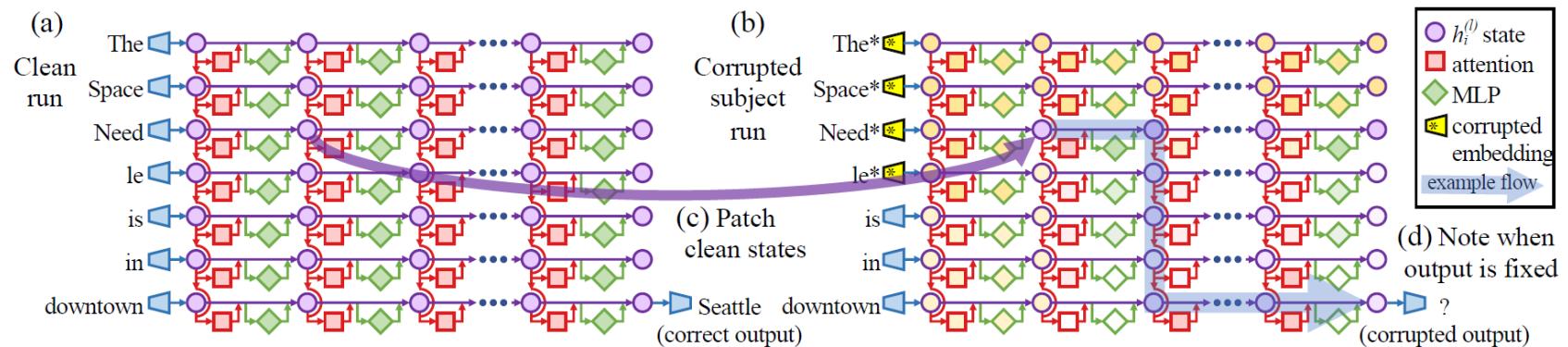
Wikitext Generation				zsRE Question-Answering				
	GPT-Neo (2.7B)		GPT-J (6B)		T5-XL (2.8B)		T5-XXL (11B)	
Editor	ES ↑	ppl. DD ↓	ES ↑	ppl. DD ↓	ES ↑	acc. DD ↓	ES ↑	acc. DD ↓
FT	0.55	0.195	0.80	0.125	0.58	<0.001	0.87	<0.001
FT+KL	0.40	0.026	0.36	0.109	0.55	<0.001	0.85	<0.001
KE	0.00	0.137	0.01	0.068	0.03	<0.001	0.04	<0.001
MEND	0.81	0.057	0.88	0.031	0.88	0.001	0.89	<0.001

FEVER Fact-Checking			zsRE Question-Answering		Wikitext Generation		Edit Success ↑		Acc. Drawdown ↓		
	BERT-base (110M)		BART-base (139M)		distilGPT-2 (82M)		Edits	ENN	MEND	ENN	MEND
Editor	ES ↑	acc. DD ↓	ES ↑	acc. DD ↓	ES ↑	ppl. DD ↓	1	0.99	0.98	<0.001	0.002
FT	0.76	<0.001	0.96	<0.001	0.29	0.938	5	0.94	0.97	0.007	0.005
FT+KL	0.64	<0.001	0.89	<0.001	0.17	0.059	25	0.35	0.89	0.005	0.011
ENN	0.99	0.003	0.99	<0.001	0.93	0.094	75	0.16	0.78	0.005	0.011
KE	0.95	0.004	0.98	<0.001	0.25	0.595	125	0.11	0.67	0.006	0.012
MEND	>0.99	<0.001	0.98	0.002	0.86	0.225					

ROME

Locating

- ▶ clean run: 正常使用prompt对语言模型进行问答。 $\mathbb{P}[o]$
- ▶ corrupted run: 对subject进行扰动。 $\mathbb{P}_*[o]$
- ▶ corrupted-with-restoration run: 恢复一些中间状态。 $\mathbb{P}_{*,clean\ h_i^{(l)}}[o]$



ROME

Locating

- ▶ clean run: 正常使用prompt对语言模型进行问答。
- ▶ corrupted run: 对subject进行扰动。
- ▶ corrupted-with-restoration run: 恢复一些中间状态。

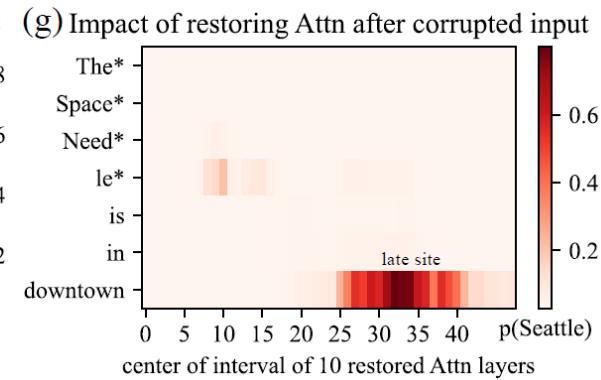
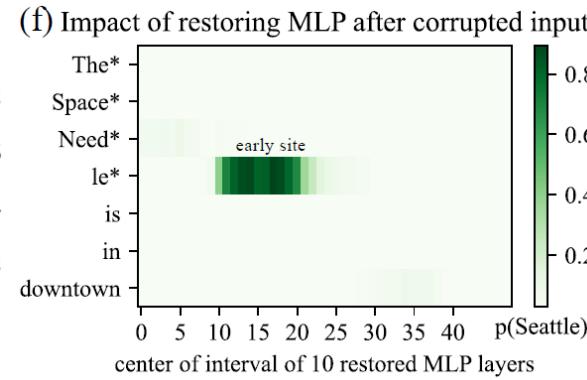
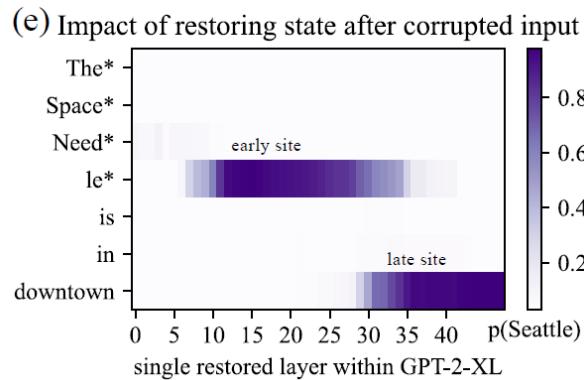
$$\mathbb{P}[o]$$

$$\mathbb{P}_*[o]$$

$$\mathbb{P}_{*, \text{clean } h_i^{(l)}}[o]$$

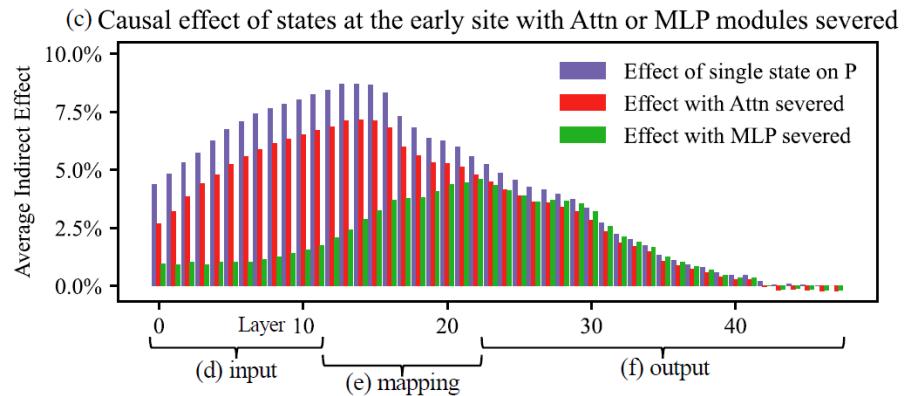
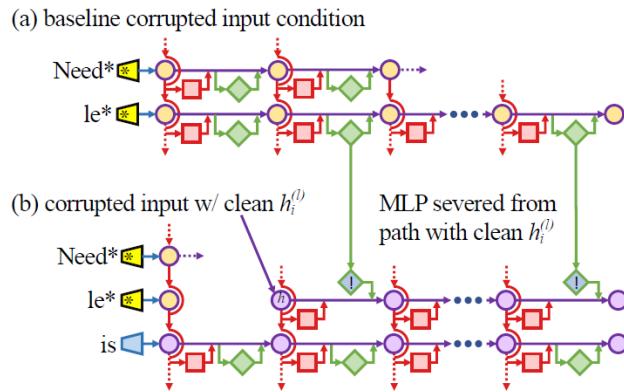
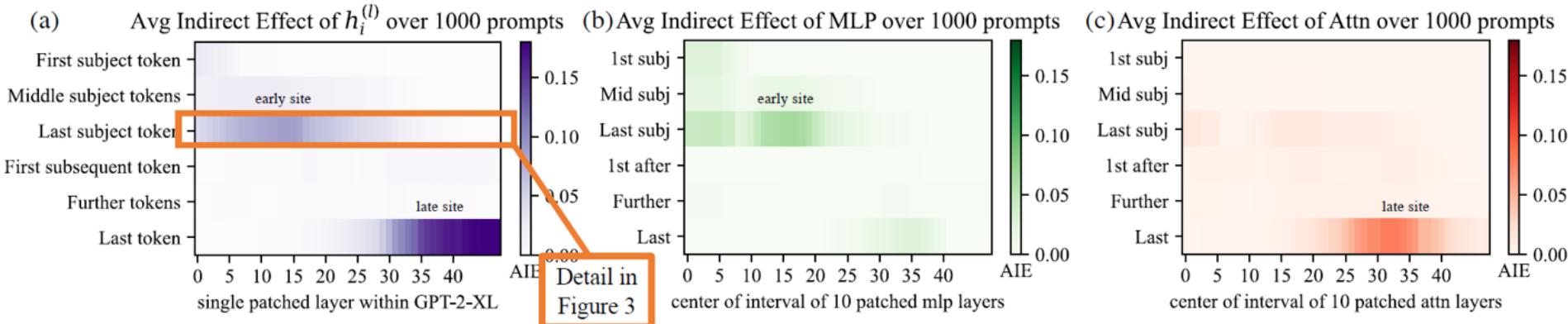
$$\text{IE} = \mathbb{P}_{*, \text{clean } h_i^{(l)}}[o] - \mathbb{P}_*[o]$$

$$\text{TE} = \mathbb{P}[o] - \mathbb{P}_*[o]$$



ROME

locating

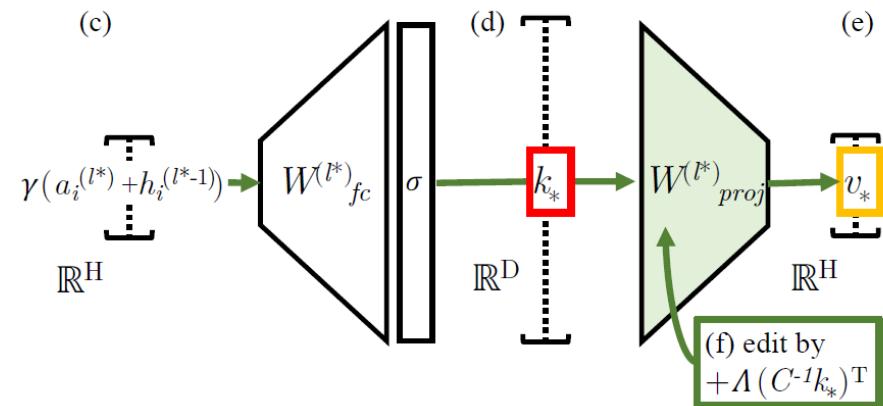
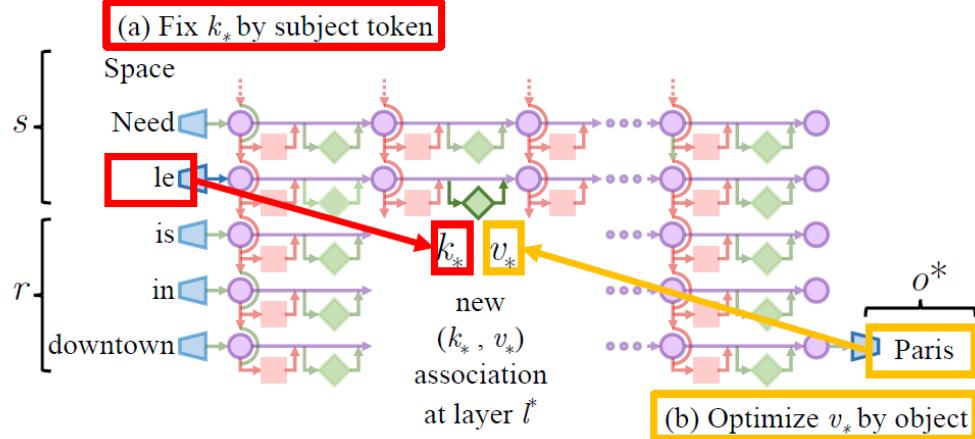


ROME

- editing

minimize $\|\hat{W}K - V\|$ such that $\hat{W}k_* = v_*$ by setting $\hat{W} = W + \Lambda(C^{-1}k_*)^T$.

$$\Lambda = (v_* - Wk_*)/(C^{-1}k_*)^T k_* \quad C = KK^T$$



ROME

editing

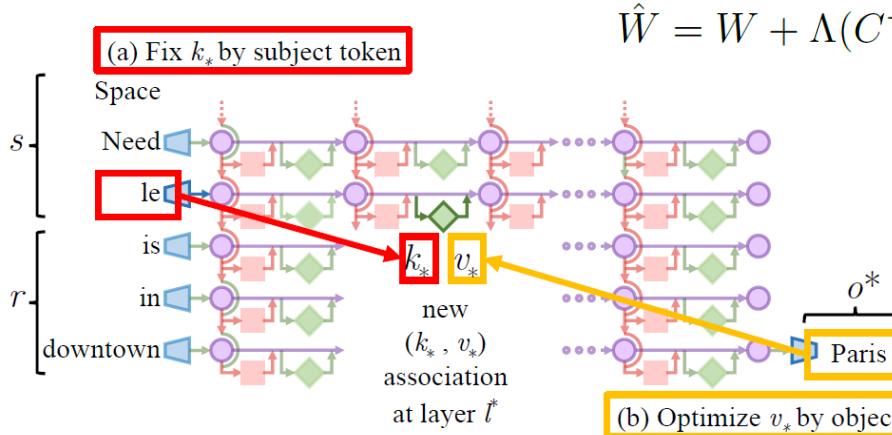
▶ 计算 k_* : 根据subject token计算 k_*

$$k_* = \frac{1}{N} \sum_{j=1}^N k(x_j + s), \text{ where } k(x) = \sigma \left(W_{fc}^{(l^*)} \gamma(a_{[x],i}^{(l^*)} + h_{[x],i}^{(l^*-1)}) \right)$$

▶ 计算 v_* :

$$\frac{1}{N} \sum_{j=1}^N \underbrace{-\log \mathbb{P}_{G(m_i^{(l^*)} := z)} [o^* | x_j + p]}_{\text{(a) Maximizing } o^* \text{ probability}} + \underbrace{D_{\text{KL}} \left(\mathbb{P}_{G(m_{i'}^{(l^*)} := z)} [x | p'] \| \mathbb{P}_G [x | p'] \right)}_{\text{(b) Controlling essence drift}}.$$

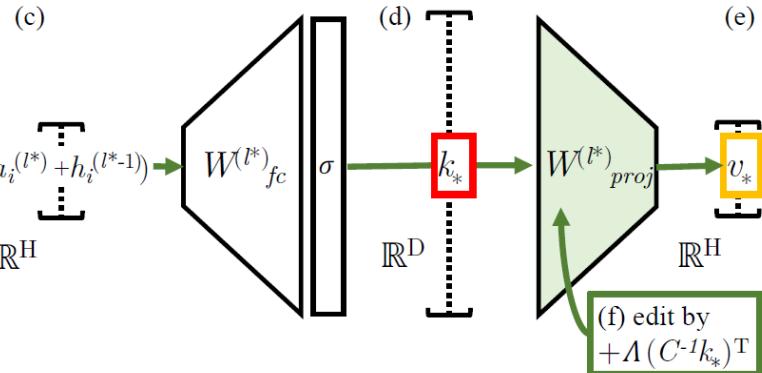
▶ 插入事实:



$$\hat{W} = W + \Lambda(C^{-1}k_*)^T$$

(c)

$$\gamma(a_i^{(l^*)} + h_i^{(l^*-1)}) \rightarrow \mathbb{R}^H$$

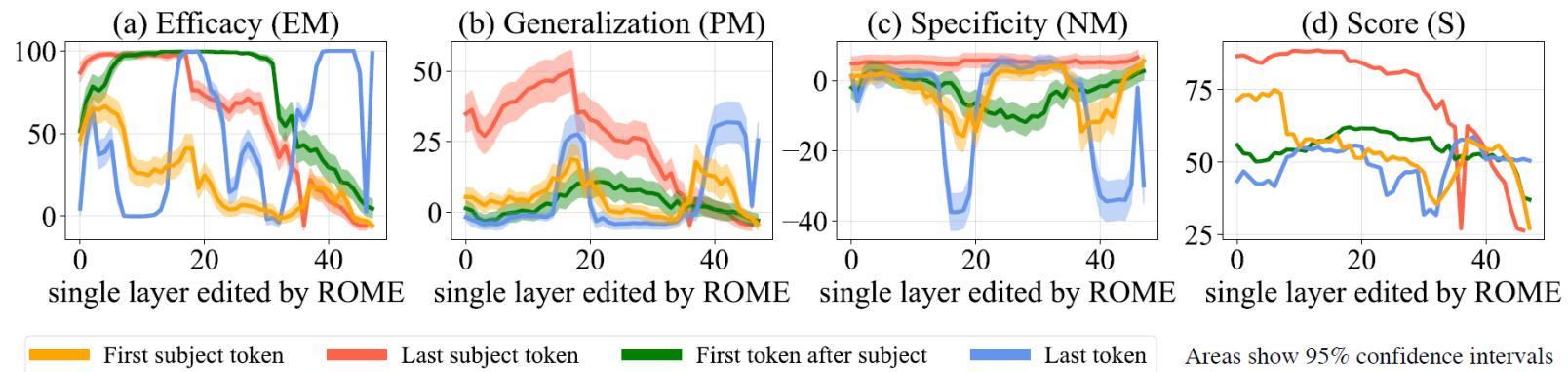


ROME

实验结果：

Table 1: zsRE Editing Results on GPT-2 XL.

Editor	Efficacy ↑	Paraphrase ↑	Specificity ↑
GPT-2 XL	22.2 (± 0.5)	21.3 (± 0.5)	24.2 (± 0.5)
FT	99.6 (± 0.1)	82.1 (± 0.6)	23.2 (± 0.5)
FT+L	92.3 (± 0.4)	47.2 (± 0.7)	23.4 (± 0.5)
KE	65.5 (± 0.6)	61.4 (± 0.6)	24.9 (± 0.5)
KE-zsRE	92.4 (± 0.3)	90.0 (± 0.3)	23.8 (± 0.5)
MEND	75.9 (± 0.5)	65.3 (± 0.6)	24.1 (± 0.5)
MEND-zsRE	99.4 (± 0.1)	99.3 (± 0.1)	24.1 (± 0.5)
ROME	99.8 (± 0.0)	88.1 (± 0.5)	24.2 (± 0.5)

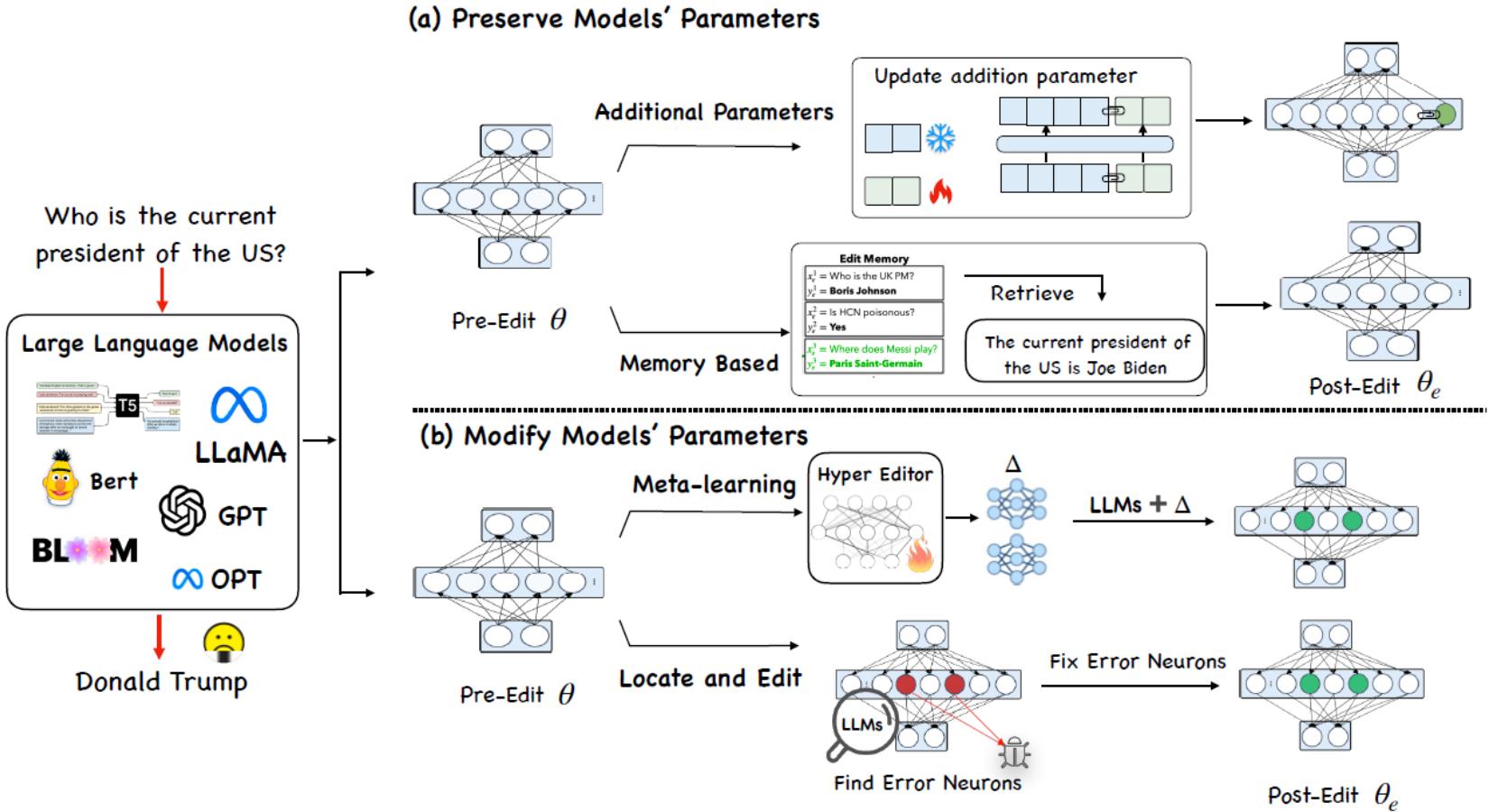


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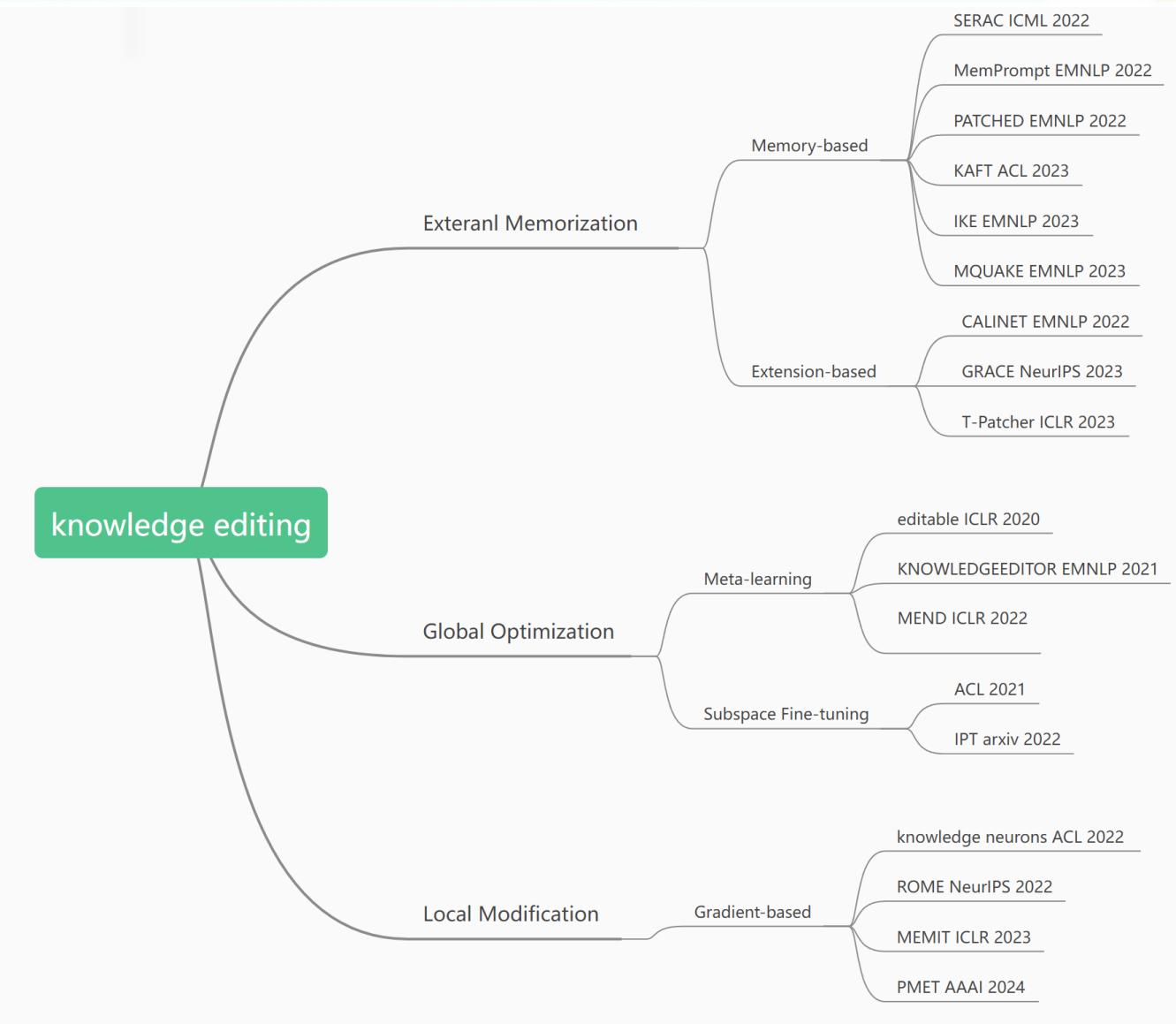
3.

总结

总结



总结



总结

- ✿ 存在挑战：

- ▶ 平衡局部性和泛化性
- ▶ 更加困难的应用场景（复杂知识、多次编辑、同时编辑）
- ▶ 理论解释

- ✿ 未来方向：

- ▶ 持续编辑
- ▶ 自动发现编辑目标
- ▶ 丰富的应用场景

总结

- ✿ paper list: <https://github.com/zjunlp/KnowledgeEditingPapers>
- ✿ ACL tutorial: Editing Large Language Models
https://drive.google.com/file/d/1EW-cusC_llCM0wEshkIdYuYrvfBPCDRz/view?usp=sharing
- ✿ 工具: EasyEdit: An Easy-to-use Knowledge Editing Framework for Large Language Models
<https://github.com/zjunlp/EasyEdit>



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谢谢大家